

Finanziato dall'Unione europea NextGenerationEU







Safe human-robot coexistence in industrial enrivonment

Spoke 1	
Task	
FP 6	Artificial intelligence, virtual reality and digital twin for advanced engineering and aerospace
Thematic line	Digital Transition
Workgroup	Gianluca Antonelli
Additional human resources	RTDa
Objective	Literature analysis on the computer vision performed through neural networks; cration of an appropriate dataset to be used with the algorithms, i.e., the neural networks architectures, selected from the state of the art.
Use case / Field of potential application	Human-robot coexistence in industrial enrivonment
Starting TRL	
Final TRL	
Collaborations	/
Connections	/